



Jade RISC-V SoC Data Sheet

DS-JADE-v1.6
December 2021
www.efinixinc.com



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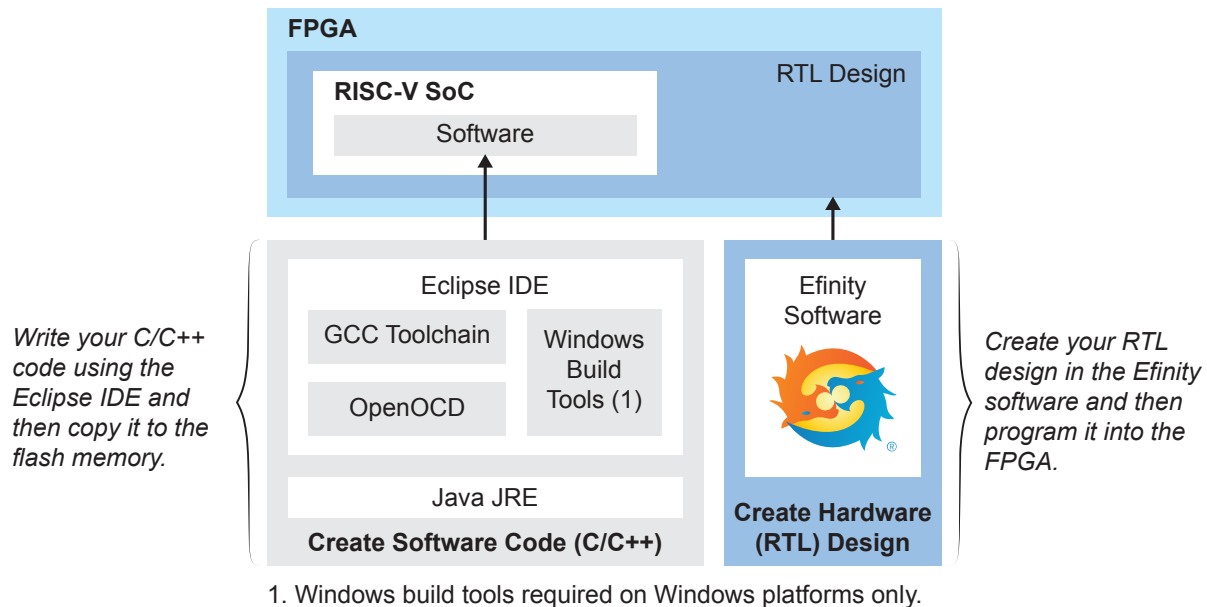
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Introduction

Efinix provides the light-weight, cached soft RISC-V SoC, Jade, that blends performance with a smaller footprint. This SoC is ideal for general-purpose applications that use triple-speed Ethernet and communications protocols, such as command and control, industrial automation, or data logging systems. Some example applications for the Jade SoC are large LED billboards and industrial controllers. This core is similar to the open-source SaxonSOC, but it has been optimized for Titanium and Trion FPGAs.

Figure 1: Jade RISC-V SoC Design Flow



Learn more: For details on developing RTL designs or creating software, refer to the [Jade RISC-V Hardware and Software User Guide](#).

VexRiscv RISC-V Core

The Jade SoC is based on the VexRiscv core created by Charles Papon. The VexRiscv core is a 32-bit CPU using the ISA RISC-V32I with M and C extensions and has five pipeline stages (fetch, decode, execute, memory, and writeback).

In the Jade SoC, the VexRiscv core supports an APB3 bus interface and has instruction and data caches.

The VexRiscv core won first place in the RISC-V SoftCPU contest in 2018.⁽¹⁾

⁽¹⁾ <https://www.businesswire.com/news/home/20181206005747/en/RISC-V-SoftCPU-Contest-Winners-Demonstrate-Cutting-Edge-RISC-V>

Features

- VexRiscv processor with 5 pipeline stages (fetch, decode, execute, memory, and write back), interrupts and exception handling with machine mode
 - 4 KB data cache
 - 4 KB instruction cache
- 20 - 350 MHz system clock frequency
- 4 - 512 KB on-chip RAM with boot loader for SPI flash
- APB3 peripherals:
 - 16 GPIOs
 - 2 I²C masters and slaves
 - Machine timer
 - PLIC
 - 2 SPI flash masters with a maximum clock frequency of 25 MHz
 - 1 UART with 115,200 baud rate
 - 1 slave user peripheral

FPGA Support

The Jade SoC supports all Titanium FPGAs and T20, T35, T55, T85, and T120 Trion FPGAs.

Titanium Resource Utilization and Performance

FPGA	Logic/Adders	FlipFlops	Memory Blocks	DSP48 Blocks	f _{MAX} (MHz)	Efinity Version
Ti60 F225 C4	4,905	2,882	26	4	274	2021.2

Trion Resource Utilization and Performance

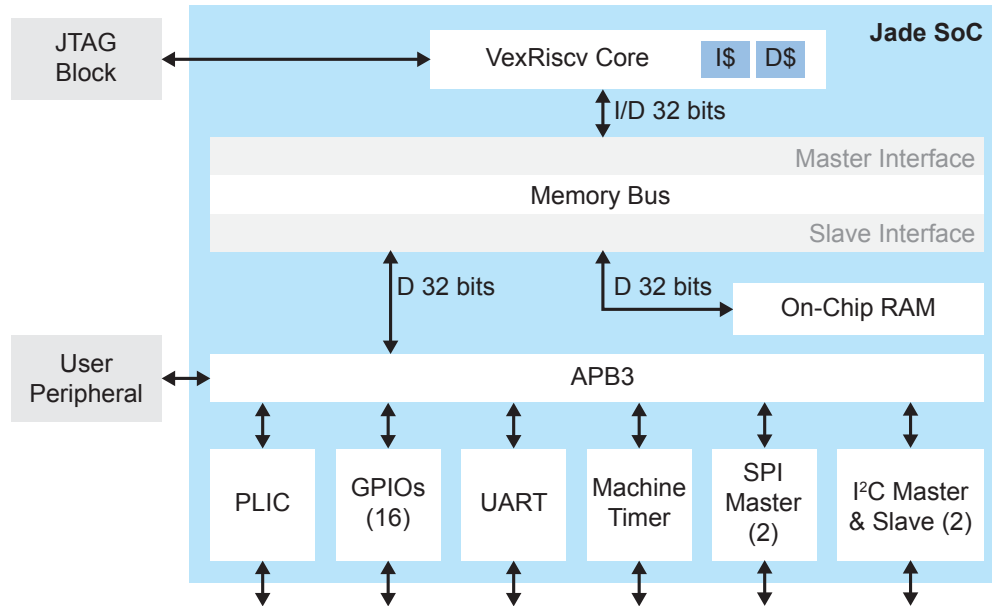
FPGA	Logic Utilization (LUTs)	Memory Blocks	f _{MAX} (MHz)	Efinity Version
T20 BGA256 C4	6,794	37	118	2021.2

Functional Description

The Jade SoC incorporates a 32-bit RISC-V processor, 4 KB instruction cache, 4 KB data cache, 4 - 512 KB of on-chip RAM, and a variety of peripherals (including 1 APB3 slave peripherals). It runs at operating frequencies of 20 - 350 MHz.

You can customize the SoC using the IP Manager in the Efinity® software v2020.2 and higher.

Figure 2: Jade SoC Block Diagram



Address Map



Note: Because the address range might be updated, Efinix recommends that you always refer to the parameter name when referencing an address in firmware, not by the actual address. The parameter names and address mappings are defined in **soc.h**.

Table 1: Default Address Map, Interrupt ID, and Cached Channels

Device	Parameter	Size	Interrupt ID	Region
GPIO	SYSTEM_GPIO_0_IO_APB	4K	[0]: 12 [1]: 13	I/O
I²C 0	SYSTEM_I2C_0_IO_APB	4K	8	I/O
I²C 1	SYSTEM_I2C_1_IO_APB	4K	9	I/O
Machine timer	SYSTEM_MACHINE_TIMER_APB	4K	31	I/O
PLIC	SYSTEM_PLIC_APB	4K	-	I/O
SPI master 0	SYSTEM_SPI_0_IO_APB	4K	4	I/O
SPI master 1	SYSTEM_SPI_1_IO_APB	4K	5	I/O

Device	Parameter	Size	Interrupt ID	Region
UART	SYSTEM_UART_0_IO_APB	4K	1	I/O
User peripheral	IO_APB_SLAVE_0_APB	64K	-	I/O
On-chip BRAM	SYSTEM_RAM_A_BMB	4 - 512 KB	-	Cache
External interrupt	-	-	25	I/O



Note: The RISC-V GCC compiler does not support user address spaces starting at 0x0000_0000.

Flash Address

When the FPGA boots up, the Jade SoC copies your binary application file from a SPI flash device to the on-chip memory, and then begins execution. The SPI flash binary address starts at 0x0038_0000.

Clocks

Table 2: Clock Ports

Port	Direction	Description
io_systemClock	Input	Provides a 20 - 350 MHz clock for the SoC.

Interrupts

Table 3: Interrupt Ports

Port	Direction	Description
userInterruptA	Input	Provides an external interrupt.

Resets

The Jade SoC has a master reset signal, `io_asyncReset` that triggers a system reset. Your RTL design should hold `io_asyncReset` for 10 ns to reset the whole SoC system completely. When you assert `io_asyncReset`, the SoC asserts:

- `io_systemReset`, which resets the RISC-V processor, on-chip memory, and peripherals

Once `io_systemReset` goes low, the user binary code is executed.

Table 4: Reset Ports

Port	Direction	Description
io_asyncReset	Input	Active-high asynchronous reset for the entire system.
io_systemReset	Output	Synchronous active-high reset for systemClk.

APB3 Interface

The following table shows the ports for the APB3 user slave peripheral. Refer to the AMBA APB Protocol Specification for APB port descriptions and handshake information.

Table 5: APB3 Ports

Port	Direction	Description
io_apbSlave_0_PADDR[15:0]	Output	User address.
io_apbSlave_0_PSEL	Output	User select.
io_apbSlave_0_PENABLE	Output	User enable.
io_apbSlave_0_PREADY	Input	User ready.
io_apbSlave_0_PWRITE	Output	User direction.
io_apbSlave_0_PWDATA[31:0]	Output	User write data.
io_apbSlave_0_PRDATA[31:0]	Input	User read data.
io_apbSlave_0_PSLVERROR	Input	User transfer failure.

JTAG Interface

The Jade SoC uses the JTAG User TAP interface block to communicate with the OpenOCD debugger.

Table 6: JTAG Ports

Port	Direction	Description
jtagCtrl_enable	Input	Indicates that the user instruction is active for the interface.
jtagCtrl_capture	Input	TAP controller is in the capture state.
jtagCtrl_shift	Input	TAP controller is in the shift state.
jtagCtrl_update	Input	TAP controller in the update state.
jtagCtrl_reset	Input	TAP controller is in the reset state.
jtagCtrl_tdi	Input	JTAG TDI for debugging.
jtagCtrl_tdo	Output	JTAG TDO for debugging.
jtagCtrl_tck	Input	JTAG TCK for debugging.

GPIO Peripheral Interface

Use the `SYSTEM_GPIO_0_IO_APB` parameter to reference the GPIO interface.

Table 7: GPIO Ports

Port	Direction	Description
<code>system_gpio_0_io_read[15:0]</code>	Input	GPIO input.
<code>system_gpio_0_io_write[15:0]</code>	Output	GPIO output.
<code>system_gpio_0_io_writeEnable[15:0]</code>	Output	GPIO output enable.

Table 8: GPIO Register Map

Address Offset	Register Name	Privilege	Width
<code>0x0000_0000</code>	Input	Read/Write	32
<code>0x0000_0004</code>	Output	Read/Write	32
<code>0x0000_0008</code>	Output Enable	Read/Write	32
<code>0x0000_0020</code>	Interrupt Rise Enable	Read/Write	32
<code>0x0000_0024</code>	Interrupt Fall Enable	Read/Write	32
<code>0x0000_0028</code>	Interrupt High Enable	Read/Write	32
<code>0x0000_002C</code>	Interrupt Low Enable	Read/Write	32

Input Register: `0x0000_0000`

31	16	15	0
Reserved		Input	

Bits	Field	Description	Privilege
0-15	Input	Set GPIO pin as an input (16 pins).	Read/Write
16-31	Reserved	Reserved.	N/A

Output Register: `0x0000_0004`

31	16	15	0
Reserved		Output	

Bits	Field	Description	Privilege
0-15	Output	Set GPIO pin as an output (16 pins).	Read/Write
16-31	Reserved	Reserved.	N/A

Output Enable Register: 0x0000_0008

31	16	15	0
Reserved			OE

Bits	Field	Description	Privilege
0-15	OE	Enable GPIO output pin (16 pins).	Read/Write
16-31	Reserved	Reserved.	N/A

Interrupt Rise Enable Register: 0x0000_0020

31	2	1	0
Reserved			IntRiseEn

Bits	Field	Description	Privilege
0-1	IntRiseEn	Enable a rise interrupt on GPIO pins 0 and 1.	Read/Write
2-31	Reserved	Reserved.	N/A

Interrupt Fall Enable Register: 0x0000_0024

31	2	1	0
Reserved			IntFallEn

Bits	Field	Description	Privilege
0-1	IntFallEn	Enable a fall interrupt on GPIO pins 0 and 1.	Read/Write
2-31	Reserved	Reserved.	N/A

Interrupt High Enable Register: 0x0000_0028

31	2	1	0
Reserved			IntHighEn

Bits	Field	Description	Privilege
0-1	IntHighEn	Enable a high interrupt on GPIO pins 0 and 1.	Read/Write
2-31	Reserved	Reserved.	N/A

Interrupt Low Enable Register: 0x0000_002C

31	2	1	0
Reserved			IntLowEn

Bits	Field	Description	Privilege
0-1	IntLowEn	Enable a low interrupt on GPIO pins 0 and 1.	Read/Write
2-31	Reserved	Reserved.	N/A

I²C Peripheral Interface

The Jade SoC has 2 I²C master/slave peripherals. Use these parameters to reference the interface:

- I²C 0—SYSTEM_I2C_0_IO_APB
- I²C 1—SYSTEM_I2C_1_IO_APB

Table 9: I²C Peripheral Ports (User)

Where *n* is 0 or 1

Port	Direction	Description
system_i2c_n_io_sda_write	Output	SDA output for user device.
system_i2c_n_io_sda_read	Input	SDA input for user device.
system_i2c_n_io_scl_write	Output	SCL output for user device.
system_i2c_n_io_scl_read	Input	SCL input for user device.

Table 10: I²C Register Map

Address Offset	Register Name	Privilege	Width
0x0000_0000	txData	Read/Write	32
0x0000_0004	txAck	Read/Write	32
0x0000_0008	rxData	Read/Write	32
0x0000_000C	rxAck	Read/Write	32
0x0000_0020	Interrupt	Read/Write	32
0x0000_0024	Interrupt Clears	Read/Write	32
0x0000_0028	Sampling Clock Divider	Read/Write	32
0x0000_002C	Timeout	Write	32
0x0000_0030	tsuData	Write	32
0x0000_0040	Master Status	Read/Write	32
0x0000_0050	tlow	Read/Write	32
0x0000_0054	tHigh	Read/Write	32
0x0000_0058	tBuf	Read/Write	32
0x0000_0080	Filtering Status	Read/Write	32
0x0000_0084	Hit Context	Read/Write	32
0x0000_0088	Filtering Configuration	Read/Write	32

txData Register: 0x0000_0000

31						12	11	10	9	8	7						0
Reserved							DisableDataConflict	repeat	enable	valid	value						

Bits	Field	Description	Privilege
0-7	value	Transmit data value.	Write
8	valid	Transmit data valid bit.	Read/Write
9	enable	Transmit data enable.	Read/Write
10	repeat	Transmit data repeat bit.	Write
11	DisableDataConflict	Disable transmit data conflict.	Write
12-31	Reserved	Reserved.	N/A

txAck Register: 0x0000_0004

31	12										11	10	9	8	7	1										0		
Reserved												DisableDataConflict	repeat	enable	valid	Reserved												value

Bits	Field	Description	Privilege
0	value	Transmit acknowledge bit.	Write
1-7	Reserved	Reserved.	N/A
8	valid	Transmit acknowledge valid bit.	Read/Write
9	enable	Transmit acknowledge enable.	Read/Write
10	repeat	Transmit acknowledge repeat bit.	Write
11	DisableDataConflict	Disable transmit acknowledge conflict.	Write
12-31	Reserved	Reserved.	N/A

rxData Register: 0x0000_0008

31	10	9	8	7	0
Reserved		listen	valid	value	

Bits	Field	Description	Privilege
0-7	value	Received data.	Read
8	valid	Receive data valid.	Read
9	listen	Start listen data.	Write
10-31	Reserved	Reserved.	N/A

rxAck Register: 0x0000_000C

31	10	9	8	7	1	0
Reserved		listen	valid	Reserved		value

Bits	Field	Description	Privilege
0	value	Received acknowledge.	Read
1-7	Reserved	Reserved.	N/A
8	valid	Receive acknowledge valid.	Read
9	listen	Start listen acknowledge.	Write
10-31	Reserved	Reserved.	N/A

Interrupt Register: 0x0000_0020

31	22	21	20	19	18	17	16	15	12	11	10	9	8	7	6	5	4	3	2	1	0		
Reserved			filterFlag	clockGenBusyFlag	Reserved		filterEnable	clockGenBusyEnable	Reserved			dropFlag	endFlag	restartFlag	startFlag	dropEnable	endEnable	restartEnable	startEnable	txAckEnable	txDataEnable	rxAckEnable	rxDataEnable

Bits	Field	Description	Privilege
0	rxDataEnable	Receive data interrupt enable	Read/Write
1	rxAckEnable	Receive acknowledge interrupt enable	Read/Write
2	txDataEnable	Transmit data interrupt enable	Read/Write
3	txAckEnable	Transmit acknowledge interrupt enable	Read/Write
4	startEnable	Start interrupt enable	Read/Write
5	restartEnable	Restart interrupt enable	Read/Write
6	endEnable	End interrupt enable	Read/Write
7	dropEnable	Drop interrupt enable	Read/Write
8	startFlag	Start interrupt flag	Read
9	restartFlag	Restart interrupt flag	Read
10	endFlag	End interrupt flag	Read
11	dropFlag	Drop interrupt flag	Read
12-15	Reserved	Reserved.	N/A
16	clockGenBusyEnable	Master clock generation interrupt enable.	Read/Write
17	filterEnable	Slave address filtering hit interrupt enable	Read/Write
18-19	Reserved	Reserved.	N/A
20	clockGenBusyFlag	Master clock generation interrupt flag.	Read
21	filterFlag	Slave address filtering hit interrupt flag.	Read
22-31	Reserved	Reserved.	N/A

Interrupt Clears Register: 0x0000_0024

31							12	11	10	9	8	7							0								
Reserved												dropFlagClear	endFlagClear	restartFlagClear	startFlagClear	Reserved											

Bits	Field	Description	Privilege
0-7	Reserved	Reserved.	N/A
8	startFlagClear	Clear start flag.	Write
9	restartFlagClear	Clear restart flag.	Write
10	endFlagClear	Clear end flag.	Write
10	dropFlagClear	Clear drop flag.	Write
12-31	Reserved	Reserved.	N/A

Timeout Register: 0x0000_002C

31	20	19	0
Reserved		value	

Bits	Field	Description	Privilege
0-19	value	Inactive timeout setting.	Write
20-31	Reserved	Reserved.	N/A

Sampling Clock Divider Register: 0x0000_0028

31	10	9	0
Reserved		samplingClockDividerWidth	

Bits	Field	Description	Privilege
0-9	samplingClockDividerWidth	Clock divider width. Controls the rate at which the I ² C controller reads SCL and SDA.	Read/Write
10-31	Reserved	Reserved.	N/A

tsuData Register: 0x0000_0030

31	6	5	0
Reserved		value	

Bits	Field	Description	Privilege
0-5	value	Data setup time.	Write
6-31	Reserved	Reserved.	N/A

Master Status Register: 0x0000_0040

31	7	6	5	4	3	1	0
Reserved						Reserved	isBusy

Bits	Field	Description	Privilege
0	isBusy	Master busy.	Read
1-3	Reserved	Reserved.	N/A
4	start	Master start.	Read/Write
5	stop	Master stop.	Read/Write
6	drop	Master drop.	Read/Write
6-31	Reserved	Reserved.	N/A

tLow Register: 0x0000_0050

31	12	11	0
Reserved		value	

Bits	Field	Description	Privilege
0-11	value	SCL low period.	Write
12-31	Reserved	Reserved.	N/A

tHigh Register: 0x0000_0054

31	12	11	0
Reserved		value	

Bits	Field	Description	Privilege
0-11	value	SCL high period.	Write
12-31	Reserved	Reserved.	N/A

tBuf Register: 0x0000_0058

31	12	11	0
Reserved		value	

Bits	Field	Description	Privilege
0-11	value	Start and stop bus free time.	Write
12-31	Reserved	Reserved.	N/A

Filtering Status Register: 0x0000_0080

31	8	7	6	5	4	3	2	1	0
Reserved		hit_7	hit_6	hit_5	hit_4	hit_3	hit_2	hit_1	hit_0

Bits	Field	Description	Privilege
0	hit_0	Filtering hit bit 0.	Read
1	hit_1	Filtering hit bit 1.	Read
2	hit_2	Filtering hit bit 2.	Read
3	hit_3	Filtering hit bit 3.	Read
4	hit_4	Filtering hit bit 4.	Read
5	hit_5	Filtering hit bit 5.	Read
6	hit_6	Filtering hit bit 6.	Read
7	hit_7	Filtering hit bit 7.	Read
8-32	Reserved	Reserved.	N/A

Hit Context Register: 0x0000_0084

31	1	0
Reserved		rw

Bits	Field	Description	Privilege
0	rw	Hit context read.	Read
1-31	Reserved	Reserved.	N/A

PLIC Peripheral Interface

Use the `SYSTEM_PLIC_APB` parameter to reference the interface PLIC interface.

Use the `SYSTEM_PLIC_CTRL` parameter to reference the interface PLIC interface.

Table 11: RISC-V PLIC Operation Parameters

Defines	Description
Interrupt priorities registers	The interrupt priority for each interrupt source.
Interrupt pending bits registers	The interrupt pending status of each interrupt source.
Interrupt enables registers	Enables the interrupt source of each context.
Priority thresholds registers	The interrupt priority threshold of each context.
Interrupt claim registers	The register to acquire interrupt source ID of each context.
Interrupt completion registers	The register to send interrupt completion message to the associated gateway.

The `soc.h` file contains a number of PLIC parameters to specify the interrupt ID for the various peripherals.

Table 12: PLIC Interrupt ID Parameters

Where n is the peripheral number and m is the interrupt ID.

Parameter	Refer to
<code>SYSTEM_PLIC_SYSTEM_I2C_n_IO_INTERRUPT m</code>	Interrupt Register: 0x0000_0020 on page 14 Interrupt Clears Register: 0x0000_0024 on page 15
<code>SYSTEM_PLIC_SYSTEM_GPIO_n_IO_INTERRUPTS_0 m</code>	Interrupt Low Enable Register: 0x0000_002C on page 10 Interrupt High Enable Register: 0x0000_0028 on page 10 Interrupt Fall Enable Register: 0x0000_0024 on page 10 Interrupt Rise Enable Register: 0x0000_0020 on page 10
<code>SYSTEM_PLIC_SYSTEM_AXI_A_INTERRUPT</code>	Interrupts on page 7
<code>SYSTEM_PLIC_SYSTEM_SPI_n_IO_INTERRUPT m</code>	Interrupt Register: 0x0000_000C on page 21
<code>SYSTEM_PLIC_SYSTEM_UART_n_IO_INTERRUPT m</code>	Status Register: 0x0000_0004 on page 23
<code>SYSTEM_PLIC_USER_INTERRUPT_A_INTERRUPT</code> <code>SYSTEM_PLIC_USER_INTERRUPT_B_INTERRUPT</code>	Interrupts on page 7

SPI Master Peripheral Interface

The SPI master peripheral interface supports traditional 4-wire SPI as well as quad-SPI mode, which sends 4 data bits per clock cycle. When implementing the SPI peripheral in traditional dual-line mode, use the `data_0` ports as MOSI and the `data_1` ports as MISO.

Use these parameters to reference the interface:

- SPI master 0—`SYSTEM_SPI_0_IO_APB`
- SPI master 1—`SYSTEM_SPI_1_IO_APB`

Table 13: SPI Master Ports

Where *n* is 0 or 1

Port	Direction	Description
<code>system_spi_n_io_sclk_write</code>	Output	SPI SCK.
<code>system_spi_n_io_data_0_writeEnable</code>	Output	SPI output enable for data 0.
<code>system_spi_n_io_data_0_read</code>	Input	SPI input for data 0.
<code>system_spi_n_io_data_0_write</code>	Output	SPI output for data 0.
<code>system_spi_n_io_data_1_writeEnable</code>	Output	SPI output enable for data 1.
<code>system_spi_n_io_data_1_read</code>	Input	SPI input for data 1.
<code>system_spi_n_io_data_1_write</code>	Output	SPI output for data 1.
<code>system_spi_n_io_data_2_writeEnable</code>	Output	SPI output enable for data 2.
<code>system_spi_n_io_data_2_read</code>	Input	SPI input for data 2.
<code>system_spi_n_io_data_2_write</code>	Output	SPI output for data 2.
<code>system_spi_n_io_data_3_read</code>	Input	SPI input for data 3.
<code>system_spi_n_io_data_3_write</code>	Output	SPI output for data 3.
<code>system_spi_n_io_data_3_writeEnable</code>	Output	SPI output enable for data 3.
<code>system_spi_n_io_ss</code>	Output	SPI SS.

Table 14: SPI Master Register Map

Address Offset	Register Name	Privilege	Width
<code>0x0000_0000</code>	Cmd	Read/Write	32
<code>0x0000_0004</code>	RSP	Read	32
<code>0x0000_0008</code>	Config	Write	32
<code>0x0000_000C</code>	Interrupt	Read/Write	32
<code>0x0000_0020</code>	ClockDivider	Write	32
<code>0x0000_0024</code>	ssSetup	Write	32
<code>0x0000_0028</code>	ssHold	Write	32
<code>0x0000_002C</code>	ssDisable	Write	32
<code>0x0000_0030</code>	ssActiveHigh	Write	32

Cmd Register: 0x0000_0000

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Bits	Field	Description	Privilege
0-7	data	FIFO data value transmit/receive.	Read/Write
8	WR	Write trigger.	Write
9	RD	Read trigger.	Write
10	Reserved	Reserved.	N/A
11	SS	SPI chip select.	Read/Write
12-31	Reserved	Reserved.	N/A

RSP Register: 0x0000_0004

31	16	15	0
fifoOccupancy		fifoAvailability	

Bits	Field	Description	Privilege
0-15	fifoAvailability	FIFO Availability.	Read
16-32	fifoOccupancy	FIFO Occupancy.	Read

Config Register: 0x0000_0008

31	2	1	0
Reserved		cpha	cpol

Bits	Field	Description	Privilege
0	cpol	Clock polarity setting.	Write
1	cpha	Clock phase setting.	Write
2-31	Reserved	Reserved.	N/A

Interrupt Register: 0x0000_000C

31	10				9	8	7	2		1	0
Reserved					rsplnt	cmdlnt	Reserved			rsplntEnable	cmdlntEnable

Bits	Field	Description	Privilege
0	cmdlntEnable	Command FIFO empty interrupt enable.	Read/Write
1	rsplntEnable	Read FIFO not empty interrupt enable.	Read/Write
2-7	Reserved	Reserved.	N/A
8	cmdlnt	Command FIFO empty interrupt pending.	Read/Write
9	rsplnt	Read FIFO not empty interrupt pending.	Read/Write
10-31	Reserved	Reserved.	N/A

clockDivider Register: 0x0000_0020

31	0
clockDivider	

Bits	Field	Description	Privilege
0-31	clockDivider	SPI frequency = FCLK / (2 * clockDivider)	Write

ssSetup Register: 0x0000_0024

31	0
ssSetup	

Bits	Field	Description	Privilege
0-31	ssSetup	Time between the chip select enable and the next byte.	Write

ssHold Register: 0x0000_0028

31	0
ssHold	

Bits	Field	Description	Privilege
0-31	ssHold	Time between the last byte transmission and the chip select disable.	Write

ssDisable Register: 0x0000_002C

31				0
ssDisable				
Bits	Field	Description	Privilege	
0-31	ssDisable	Time between the chip select disable and the chip select enable.	Write	

ssActiveHigh Register: 0x0000_0030

31				0
ssActiveHigh				
Bits	Field	Description	Privilege	
0-31	ssActiveHigh	These bits correspond to the hardware SPI chip select. 0: Chip select is active low. 1: Chip select is active high.	Write	

UART Peripheral Interface

The UART peripheral runs at 115200 baud and supports 8 data bits, no parity, and 1 stop bit. Use the `SYSTEM_UART_0_IO_APB` parameter to reference the interface.

Table 15: UART Ports

Port	Direction	Description
system_uart_0_io_txd	Output	UART 0 transmit.
system_uart_0_io_rxd	Input	UART 0 receive.

Table 16: SPI Master Register Map

Address Offset	Register Name	Privilege	Width
0x0000_0000	Data	Read/Write	32
0x0000_0004	Status	Read/Write	32
0x0000_0008	Clock divider	Read/Write	32
0x0000_000C	Config register	Read/Write	32

Data Register: 0x0000_0000

31				0
data				
Bits	Field	Description	Privilege	
0-31	data	Stores data that is transmitted or received.	Read/Write	

Status Register: 0x0000_0004

31	24	23	16	15	2	1	0
readOccupancy				writeAvailability			Reserved
							RXInterrupt
							TXInterrupt

Bits	Field	Description	Privilege
0	TXInterrupt	Interrupt when TX FIFO is empty.	Read/Write
1	RXInterrupt	Interrupt when RX FIFO is not empty.	Read/Write
2-15	Reserved	Reserved.	N/A
16-23	writeAvailability	UART FIFO availability.	Read/Write
24-31	readOccupancy	UART FIFO occupancy.	Read/Write

Clock Divider Register: 0x0000_0008

31	0
DividerFactor	

Bits	Field	Description	Privilege
0-31	DividerFactor	Divider factor for the UART baud rate. Baudrate = SystemClk/(Data Length * DividerFactor)	Read/Write

Config Register: 0x0000_000C

31	17	16	15	9	8	7	0
Reserved				Stop	Reserved		Parity
							DataLength

Bits	Field	Description	Privilege
0-7	DataLength	Data length.	Read/Write
8	Parity	Parity bit number.	Read/Write
9-15	Reserved	Reserved.	
16	Stop	Stop bit number.	Read/Write
17-32	Reserved	Reserved.	N/A

Control and Status Registers

The following tables show the machine-level CSR implementation.

Table 17: Machine Information Register

Address	Register Name	Privilege	Description	Width
0xF14	mhartid	Read	Hardware thread ID.	32

Table 18: Machine Trap Registers

Address	Register Name	Privilege	Description	Width
0x300	mstatus	Read/Write	Machine status register.	13
0x304	mie	Read/Write	Machine interrupt enable register.	12
0x305	mtvec	Read/Write	Machine trap handler base address.	32

Table 19: Machine Trap Handling Registers

Address	Register Name	Privilege	Description	Width
0x341	mpec	Read/Write	Machine exception program counter.	32
0x342	mcause	Read	Machine trap cause.	32
0x343	mtval	Read	Machine bad address or instruction.	32
0x344	mip	Read/Write	Machine interrupt pending.	12

Machine-Level ISA

Hart ID Register (mhartid): 0xF14

The `mhartid` CSR is a 32-bit read-only register containing the integer ID of the hardware thread running the code. This register must be readable in any implementation. Hart IDs might not necessarily be numbered contiguously in a multiprocessor system, but at least one hart must have a hart ID of zero. Hart IDs must be unique.

31	0
Hart ID	

Bits	Field	Description	Privilege
0-31	Hart ID	Hardware thread ID.	Read

Machine Status Register (*mstatus*): 0x300

The *mstatus* register is a 13-bits read/write register formatted. The *mstatus* register keeps track of and controls the hart's current operating state. Restricted views of the *mstatus* register appear as the *sstatus* and *ustatus* registers in the S-level and U-level ISAs, respectively.

12	11	10	9	8	7	6	5	4	3	2	1	0
MPP	Reserved			MPIE	Reserved			MIE	Reserved			

Bits	Field	Description	Privilege
0-2	Reserved	Reserved.	N/A
3	MIE	Machine interrupt enable register.	Read/Write
4-6	Reserved	Reserved.	N/A
7	MPIE	Machine previous interrupt enable.	Read/Write
8-10	Reserved	Reserved.	N/A
11-12	MPP	Machine Previous privilege mode.	Read/Write

Machine Trap-Vector Base-Address Register (*mtvec*): 0x305

The *mtvec* register is a 32-bit read/write register that holds trap vector configuration, consisting of a vector base address (base) and a vector mode (mode).

31											2	1	0
base												mode	

Bits	Field	Description	Privilege
0-1	mode	Vector mode. 0: Direct. All exceptions set pc to BASE 1: Vectored. Asynchronous interrupts set pc to BASE + 4xcause ≥ 2: Reserved	Read/Write
2-31	base	Vector base address.	Read/Write

Machine Interrupt Enable Register (*mie*): 0x304

The *mie* register is a 12-bit read/write register containing interrupt enable bits.

11	10	9	8	7	6	5	4	3	2	1	0
MEIE	Reserved			MTIE	Reserved			MSIE	Reserved		

Bits	Field	Description	Privilege
0-2	Reserved	Reserved.	N/A
3	MSIE	Machine software interrupt enable.	Read/Write
4-6	Reserved	Reserved.	N/A
7	MTIE	Machine timer interrupt enable.	Read
8-10	Reserved	Reserved.	N/A
11	MEIE	Machine external interrupt enable.	Read

Machine Exception Program Counter (mepc): 0x341

mepc is a 32-bit read/write register. The low bit of mepc (mepc[0]) is always zero. On implementations that support only IALIGN=32, the two low bits (mepc[1:0]) are always zero.

31	0
mepc	

Bits	Field	Description	Privilege
0-31	mepc	Machine exception program counter.	Read/Write

Machine Cause Register (mcause): 0x342

The mcause register is a 32-bit read-write register. When a trap is taken into M-mode, mcause is written with a code indicating the event that caused the trap. Otherwise, mcause is never written by the implementation, though it may be explicitly written by software.

31	30	0
Interrupt	Exception Code	

Bits	Field	Description	Privilege
0-30	Exception code	See Table 20: Machine Cause Register (mcause) Values after Trap on page 26.	Read
31	Interrupt	mcause interrupt bit.	Read

Table 20: Machine Cause Register (mcause) Values after Trap

Interrupt	Exception Code	Description
1	0	Reserved.
1	1	Supervisor software interrupt.
1	2	Reserved.
1	3	Machine software interrupt.
1	4	User timer interrupt.
1	5	Supervisor timer interrupt.
1	6	Reserved.
1	7	Machine timer interrupt.
1	8	User external interrupt.
1	9	Supervisor external interrupt.
1	10	Reserved.
1	11	Machine external interrupt.
1	≥12	Reserved.
0	0	Instruction address misaligned.
0	1	Instruction access fault.
0	2	Illegal instruction.
0	3	Breakpoint.

Interrupt	Exception Code	Description
0	4	Load address misaligned.
0	5	Load access fault.
0	6	Store/AMO address misaligned.
0	7	Store/AMO access fault.
0	8	Reserved.
0	9	Reserved.
0	10	Reserved.
0	11	Environment call from M-mode.
0	12	Instruction page fault.
0	13	Load page fault.
0	14	Reserved.
0	15	Store/AMO page fault.
0	≥16	Reserved.

Machine Trap Value Register (mtval): 0x343

The `mtval` register is a 32-bit register. When a trap is taken into M-mode, `mtval` is either set to zero or written with exception-specific information to assist software in handling the trap. Otherwise, `mtval` is never written by the implementation, though it may be explicitly written by software. The hardware platform will specify which exceptions must set `mtval` informatively and which may unconditionally set it to zero.

31	0
mtval	

Bits	Field	Description	Privilege
0-31	mtval	Machine trap value register bit.	Read/Write

Machine Interrupt Pending Register (mip): 0x344

The `mip` register is a 12-bit read/write register containing information on pending interrupts.

11	10	9	8	7	6	5	4	3	2	1	0
MEIP	Reserved			MTIP	Reserved			MSIP	Reserved		

Bits	Field	Description	Privilege
0-2	Reserved	Reserved.	N/A
3	MSIP	Machine software interrupt pending.	Read/Write
4-6	Reserved	Reserved.	N/A
7	MTIP	Machine timer interrupt pending.	Read
8-10	Reserved	Reserved.	N/A
11	MEIP	Machine external interrupt pending.	Read

Revision History

Table 21: Revision History

Date	Version	Description
December 2021	1.6	Updated resource numbers.
September 2021	1.5	The SoC minimum frequency changed to 20 MHz. (DOC-544)
July 2021	1.4	Updated for the Efinity v2021.1 release. Updated the SoC f_{MAX} range. Updated the GPIO register descriptions. (DOC-475)
March 2021	1.3	Updated SoC operating frequency. Updated on-chip RAM size.
November 2020	1.2	Added UART register descriptions. Updated the address map to show parameters instead of address ranges.
August 2020	1.1	User peripheral address size changed to 64K. io_apbSlave_PADDR size changed to 15:0. Corrected typos.
June 2020	1.0	Initial release.